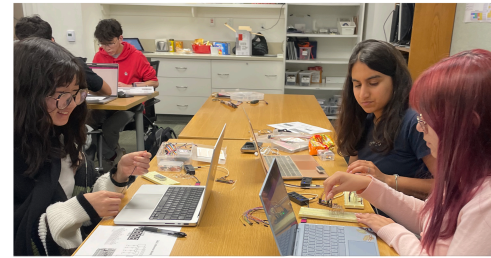
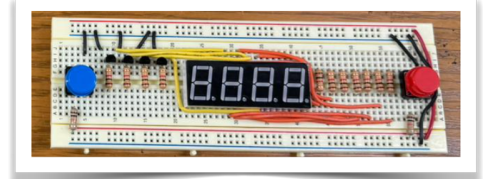


# Admin

## Important fix:

Assign2 starter code  
`test_breadboard`  
`gpio segment/digit`  
arrays are crossed  
(see Ed post)



## Today: C functions

Implementation of C function calls

Management of runtime stack, register use



**loop:**

```
sw      a1,0x40(a0)
lui     a2,0x3f00
delay:
addi    a2,a2,-1
bne     a2,zero,delay
```

```
sw      zero,0x40(a0)
lui     a2,0x3f00
delay2:
addi    a2,a2,-1
bne     a2,zero,delay2
```

**j loop**

*Repeated code,  
would be nice to unify...*



loop:

```
sw    a1,0x40(a0)
```

```
j     pause
```

```
sw    zero,0x40(a0)
```

```
j     pause
```

```
j     loop
```

```
pause:
```

```
    lui    a2,0x3f00
```

```
delay:
```

```
    addi   a2,a2,-1
```

```
    bne    a2,zero,delay
```

```
// but... where to go now?
```

loop:

```
sw    a1,0x40(a0)
jal   ra,pause
```

```
sw    zero,0x40(a0)
jal   ra,pause
```

```
j     loop
```

*How to remember  
where we came from, so  
we can go back there...*

```
pause:
    lui    a2,0x3f00
delay:
    addi   a2,a2,-1
    bne    a2,zero,delay
    jr     ra
```

loop:

```
sw    a1,0x40(a0)
lui   a2,0x3f00
jal   ra,pause
```

```
sw    zero,0x40(a0)
lui   a2,0x3f00
jal   ra,pause
```

```
j     loop
```

*How to communicate  
arguments to function?*

```
pause:
delay:
    addi    a2,a2,-1
    bne     a2,zero,delay
    jr      ra
```



# New instructions

## Jump and Link **jal**

Saves pc+4 into rd before jump to target (pc-relative offset)

```
jal rd,imm           // rd = pc+4, pc = pc+imm
```

## Jump and Link Register **jalr**

Saves pc+4 into rd before jump to target (register + offset)

```
jalr rd,imm(rs1)     // rd = pc+4, pc = rs1+imm
```

## Also add upper immediate to PC **auipc**

```
auipc rd,imm         // rd = pc + imm<<12
```

## Pseudo-instructions

```
call fn    -> jal ra,fn  
jr rs1     -> jalr zero,0(rs1)  
ret        -> jalr zero,0(ra)
```

# Anatomy of C function call

```
int factorial(int n)
{
    int result = 1;
    for (int i = n; i > 1; i--)
        result *= i;
    return result;
}
```

**Call and return**

**Pass arguments**

**Local variables**

**Return value**

**Scratch/work space**

*Complication: nested function calls, recursion*

# Application binary interface

ABI specifies how code interoperates:

- Mechanism for call/return
- How parameters passed
- How return value communicated
- Use of registers (ownership/preservation)
- Stack management (up/down, alignment)



# Mechanics of call/return

Caller stores up to 8 arguments in a0 - a7

**call** (jal) saves pc+4 to ra and jump to target

```
li a0,100
li a1,7
call fn
```

```
sum(100, 7);
```

```
int sum(int a, int b) {
    return a + b;
}
```

Callee stores return value in a0

**ret** (jalr) jumps back to ra

```
add a0,a0,a1
ret
```

# Caller and Callee

**caller:** function doing the calling

**callee:** function being called

main is caller of range

range is callee of main

range is caller of abs

```
void main(void) {  
    range(13, 99);  
}
```

```
int range(int a, int b) {  
    return abs(a-b);  
}
```

```
int abs(int v) {  
    return v < 0 ? -v : v;  
}
```

# Register Ownership

$a0-a7$ ,  $t0-t6$  are **callee-owned** registers

- **Callee** can freely use/modify these registers
- **Caller** cedes to callee, has no expectation of register contents after call

$S0-s11$  are **caller-owned** registers

- **Caller** retains ownership, expects register contents to be same after call as it was before call
- **Callee** cannot use/modify these registers unless takes steps to preserve/restore values



# Discuss...

1. If callee needs scratch space for an intermediate result, which type of register should it choose?
2. Why might a callee need to use a caller-owned register? What does callee have to do if using one?
3. What is the advantage in having some registers callee-owned and others caller-owned? Wouldn't it be simpler if all treated the same?

# The stack to the rescue!

Reserve section of memory to store data for executing function

Stack frame allocated per function invocation

Can store local variables, scratch values, saved registers

- `sp` points to lastmost value pushed
- stack grows down
  - Decrement `sp` at function entry makes space for stack frame ("push")
  - Access frame variables using `sp`-relative offset
  - Increment `sp` at function exit to clean up frame ("pop")
- Call stack is LIFO, last frame pushed is first frame popped

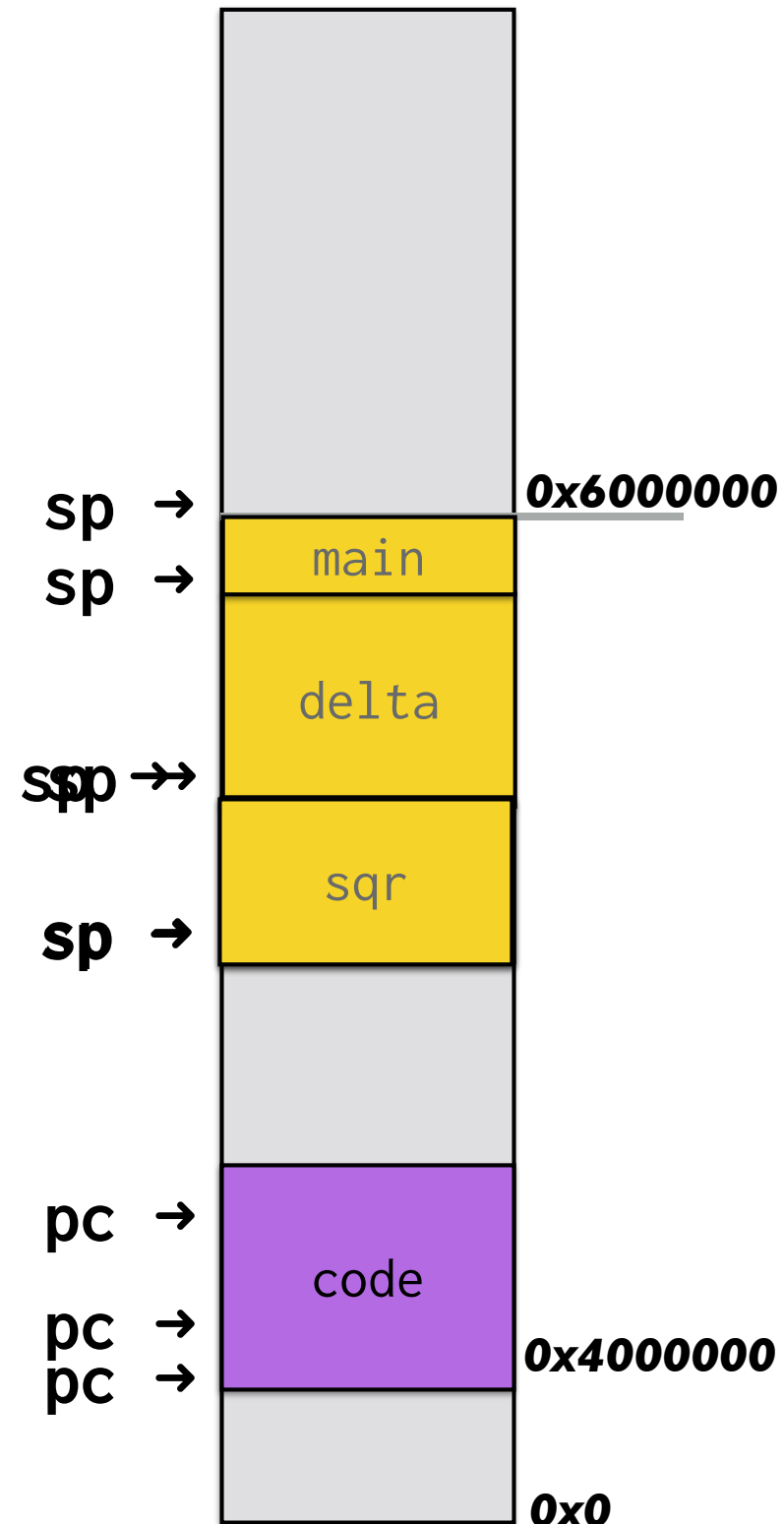
```
// start.s
lui    sp,0x6000
call   main
```

```
void main(void)
{
    delta(3, 7);
}
```

```
int delta(int a, int b)
{
    int diff = sqr(a) - sqr(b);
    return diff;
}
```

```
int sqr(int v)
{
    return v * v;
}
```

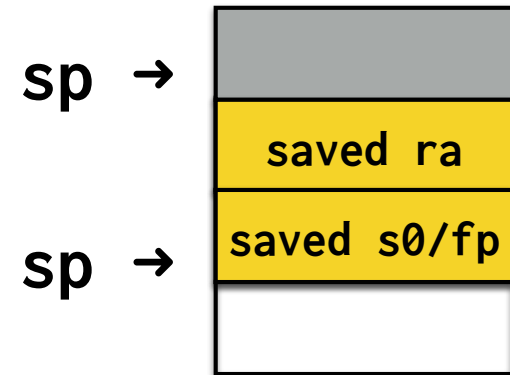
*Diagram not to scale*





# Stack operation

```
addi    sp, sp, -16
sd       ra, 8(sp)
sd       s0, 0(sp)
addi     s0, sp, 16
mv       a1, a0
call     sum
ld       ra, 8(sp)
ld       s0, 0(sp)
add      sp, sp, 16
ret
```



# Gdb debugger

## **Debugger is incredibly useful**

Allows you to run your program in a monitored context  
Can set breakpoints, examine state, change values,  
reroute control, and more

`gdb` has simulation mode where it pretends to be an  
RISC-V processor, running on your laptop 🙌🙌

Pretty good approximation (not perfect, e.g. no  
peripherals)

# C vs Assembly Smackdown

## Why C?

- Variable names, type system

- Function decomposition, control flow

- Portable abstractions

- Consistent semantics

- Compiler back-end doing heavy lifting - yay!

## Why assembly?

- Execution is always in asm, this is the real deal -- WYSIWYG

- Ability to drop down and review/debug asm is key

- Certain hardware features only accessible via asm

- Hand-code in asm for optimization or obtain precise timing