

# Admin

Wrap of assignments 

Bug Fix Party  today 2-5pm

Final deadline for re-test fixes and full system **5pm Sun Nov 24**

## Onto ... projects!

Proposals due now, add to Amazon group order by Monday

## Today: Output

Use gpio to drive outputs

Communicate, make sounds, control servos/motors, ...

Digital to analog conversion

# GPIO output

**GPIO pin is for digital signal (very little power)**

3.3V logic level

Pi can supply max current  $\sim 50\text{mA}$  across all pins

Max total power 0.165W

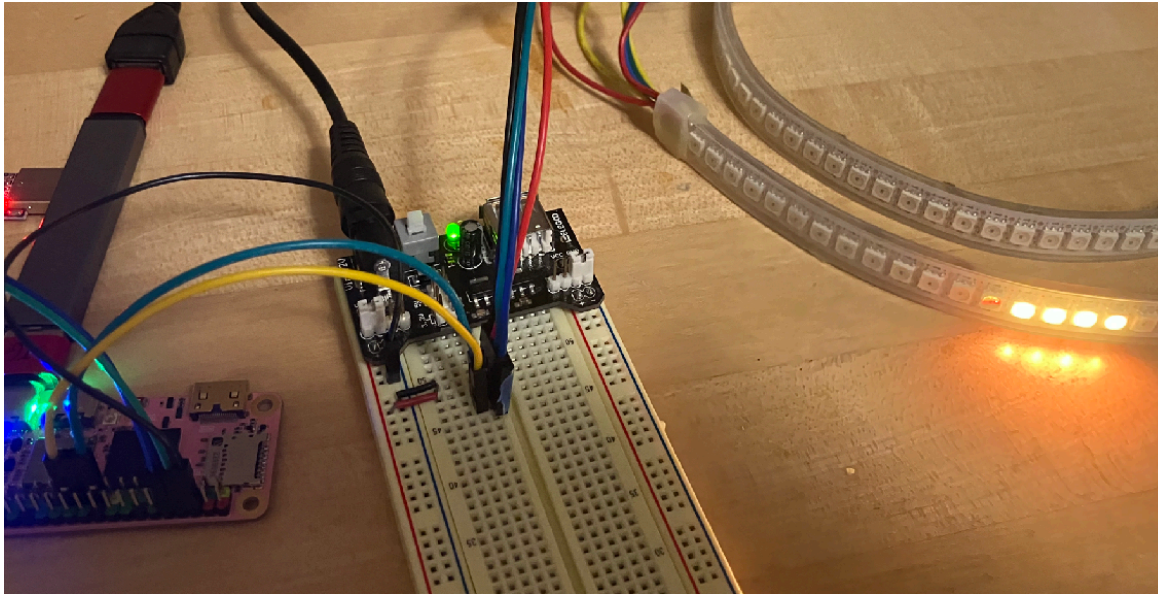
**Output devices often need more power**

High-power LEDs, long LED strips, motors, speakers, etc.

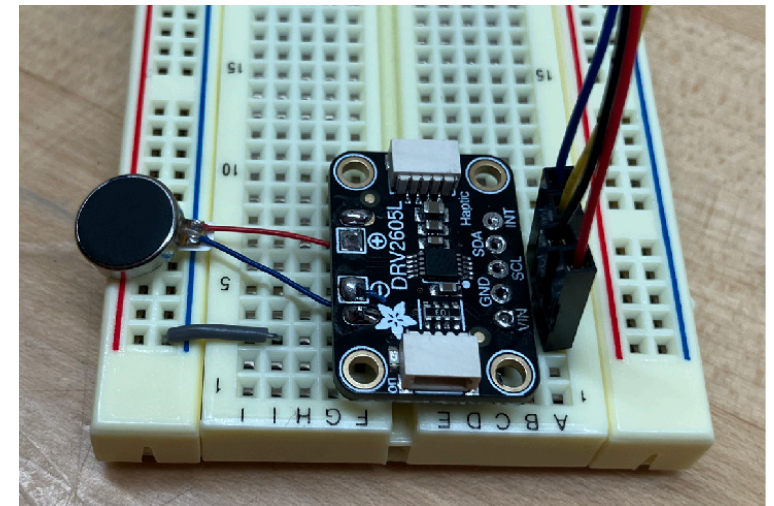
**Attempt to drive via gpio can fail and/or damage Pi**

Calculate power requirements and select appropriate power source (DC wall adapter, battery pack)

# Demo: SPI & I2C

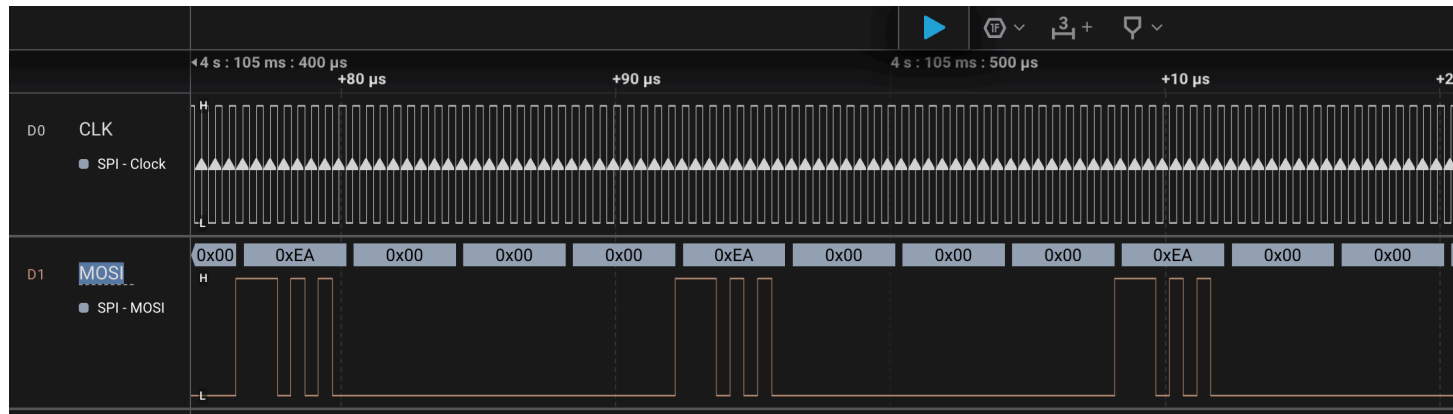


SPI: APA102 DotStar RGB led strip

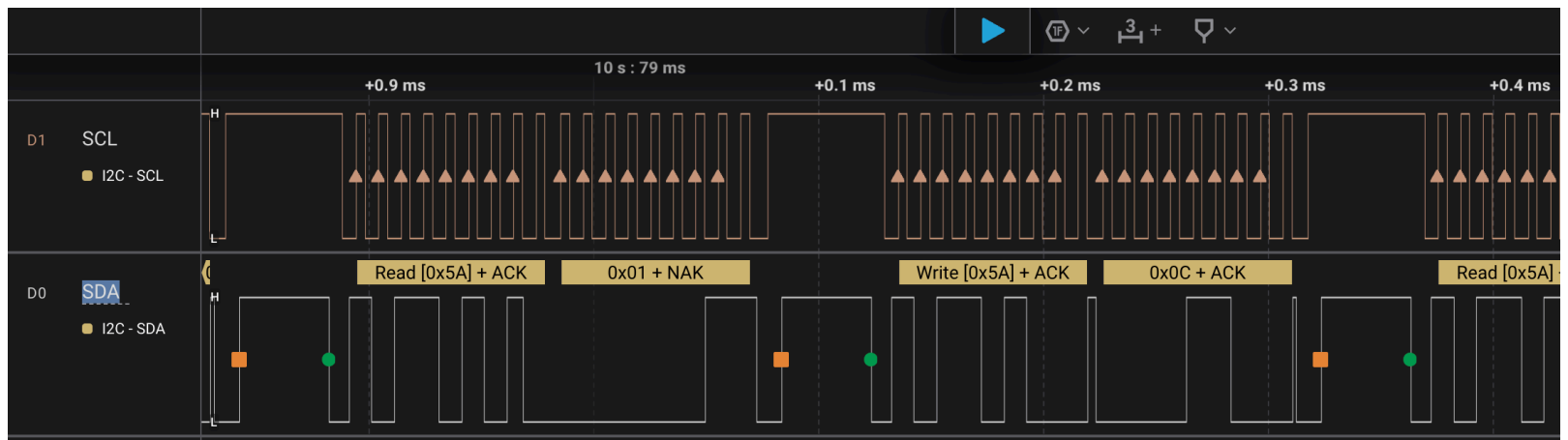


I2C: DRV2605 haptic vibration controller

# Logic Analyzer FTW



SPI: APA102 DotStar RGB led strip



I2C: DRV2605 haptic vibration controller

# GPIO output is digital

Configure pin as output, write 1 or 0

What can a high/low voltage signal?

Turn on/off: led, transistor, relay

Single bit in comm protocol such as UART or PS/2

How to turn voltage into motion, sound, radio, ...

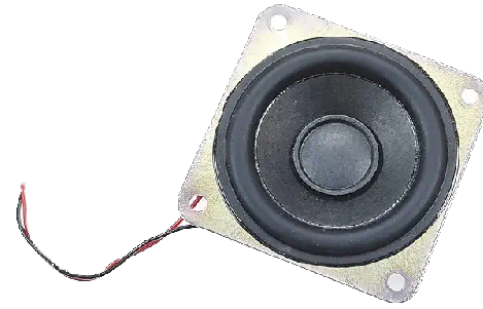
# Electromagnetism in action!



Piezoelectric disk



Passive buzzer



Speaker



Electromagnet



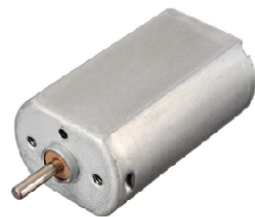
Solenoids



Linear actuator



Vibrating disk



DC motor



Stepper motor



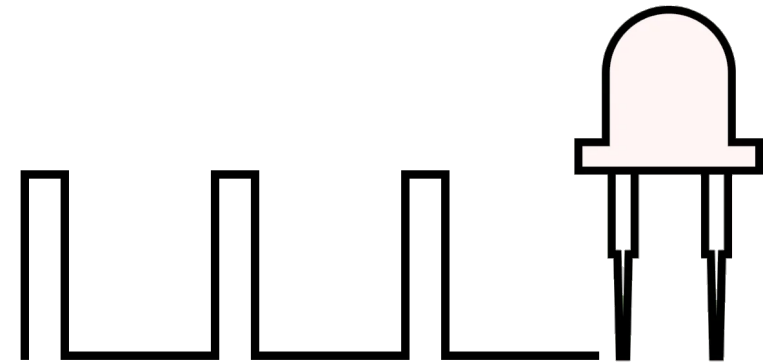
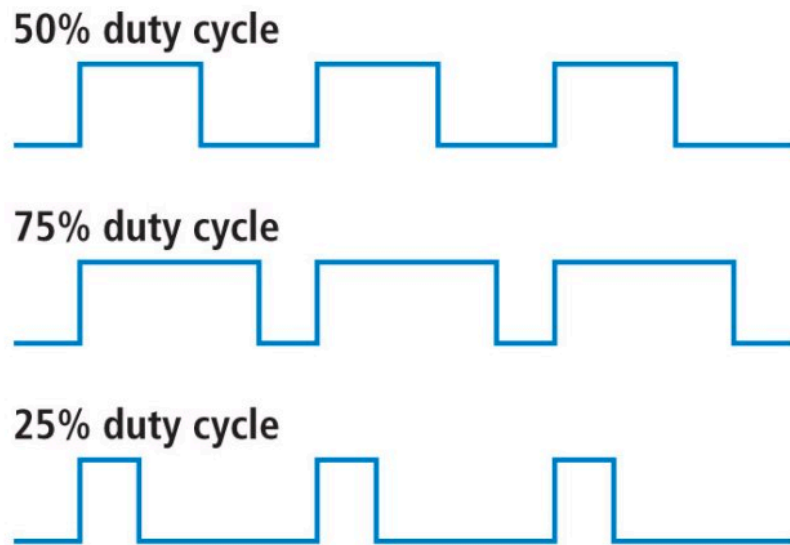
Servo

Demo: electromagnet, solenoid

**How to synthesize analog signal  
from digital hardware?**

***Digital-to-analog conversion (DAC)***

# Pulse-width modulation (PWM)



Generate square wave of given frequency

Duty cycle = ratio on/off in one period

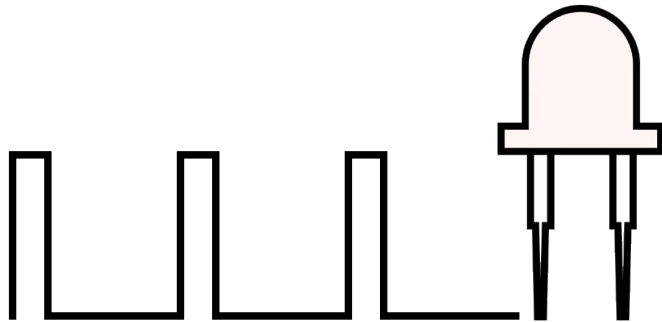
*Higher/lower frequency — what is effect?*

*Smaller/larger duty cycle — what is effect?*



# Demo: Software PWM

Code to "bit-bang" gpio pin



Ramp led on/off

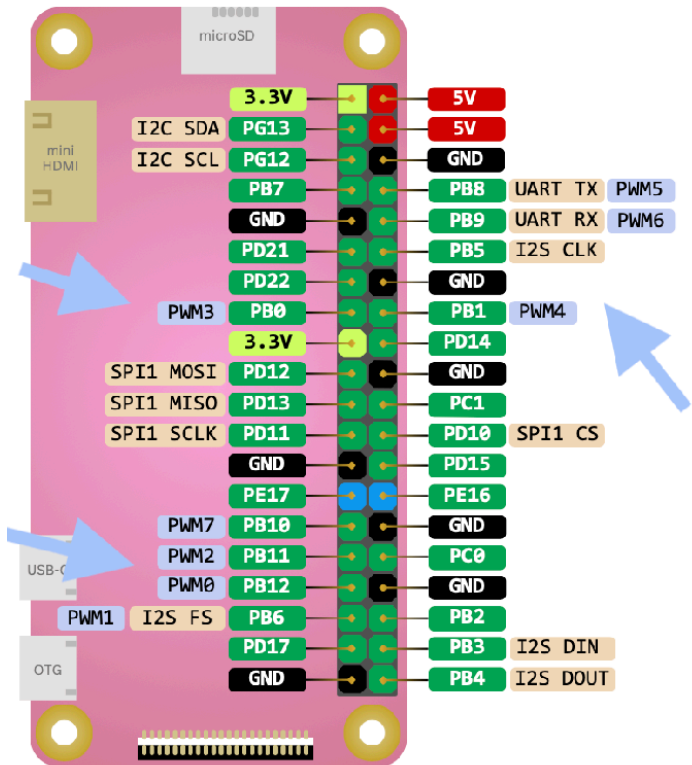
```
for (int i = 0; i < n; i++) {  
    gpio_write(pin, 1);  
    timer_delay_us(on_time);  
    gpio_write(pin, 0);  
    timer_delay_us(off_time);  
}
```

*(Q:What happens if substitute motor or buzzer for led?)*



Works, but ... CPU consumed with timing-sensitive task

# Hardware PWM



Confidential

## 9.11 PWM

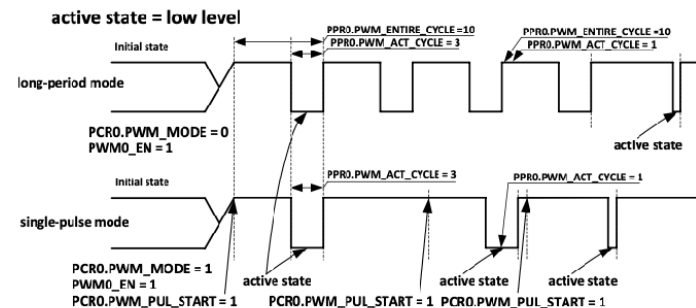
### 9.11.1 Overview

The Pulse Width Modulation (PWM) module can output the configurable PWM waveforms and measure the external input waveforms.

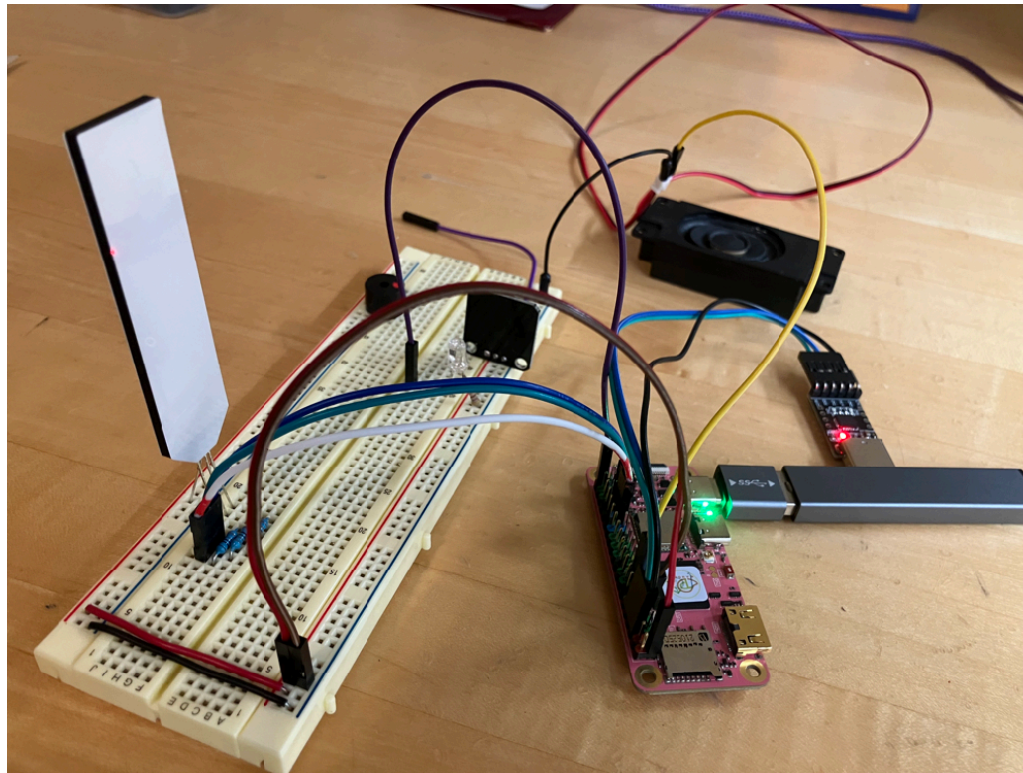
The PWM has the following features:

- Supports 8 independent PWM channels (PWM0 to PWM7)
  - Supports PWM continuous mode output
  - Supports PWM pulse mode output, and the pulse number is configurable
  - Output frequency range: 0 to 24 MHz or 100 MHz
  - Various duty-cycle: 0% to 100%
  - Minimum resolution: 1/65536
- Supports 4 complementary pairs output

Figure 9-89 PWM0 Output Waveform in Pulse Mode and Cycle Mode



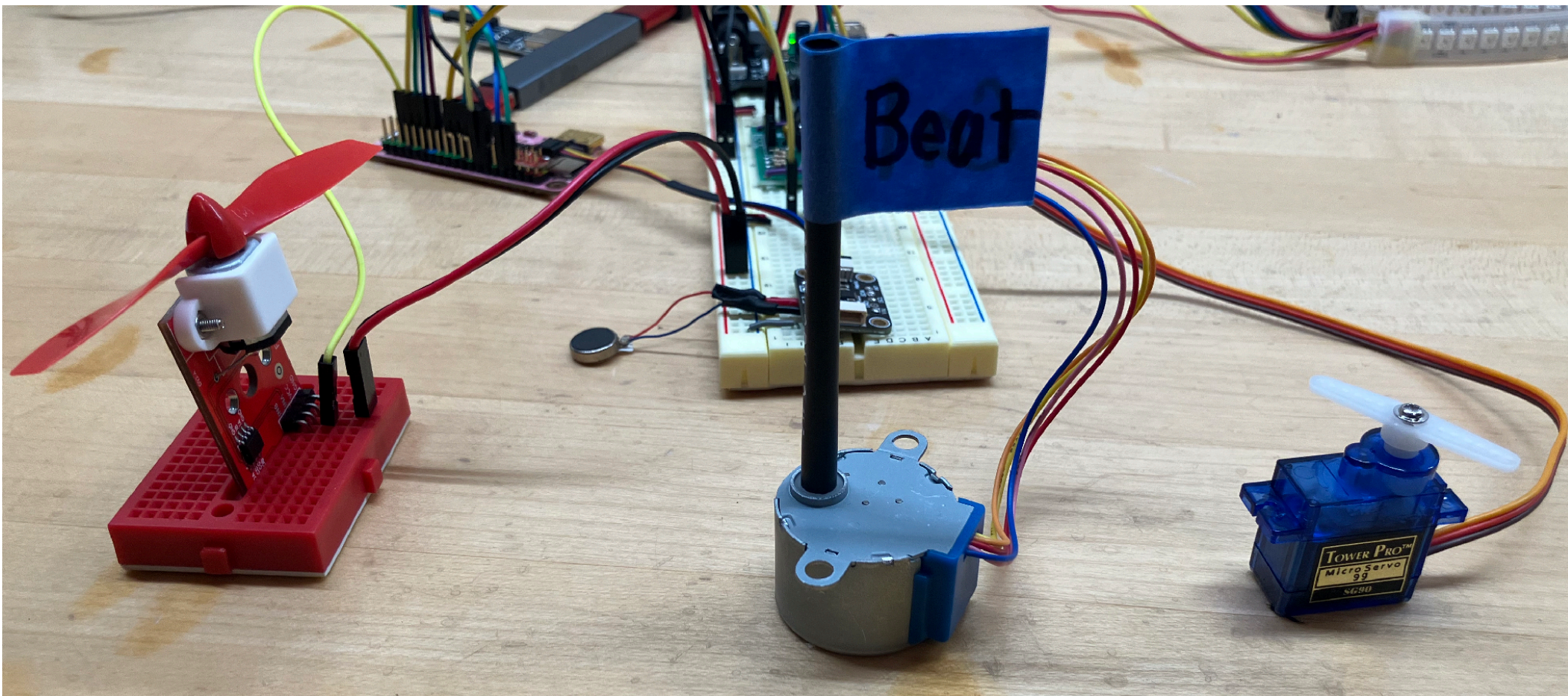
# Demo: Hardware PWM



RGB led

Square wave tones and sound effects

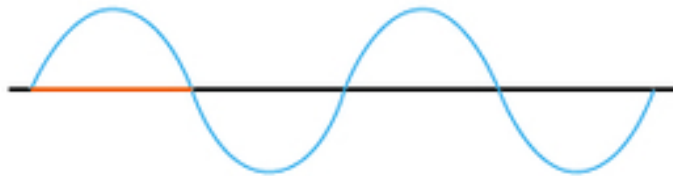
# Demo: Motors



DC motor, stepper, servo

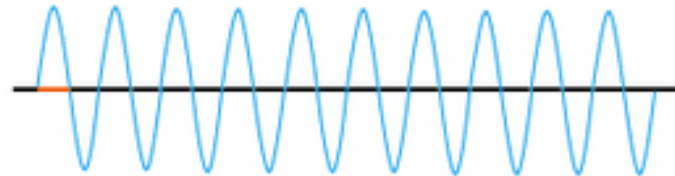
# Sound Waves

Lower Pitch



Low Frequency

Higher Pitch



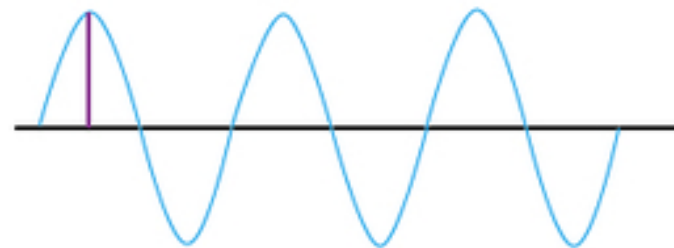
High Frequency

Quieter



Low Amplitude

Louder

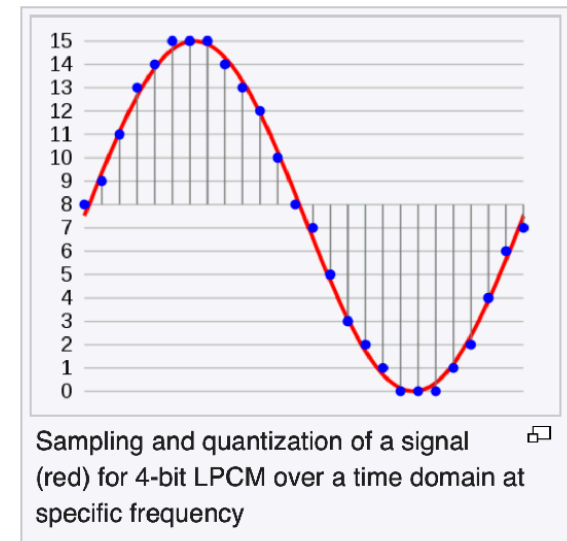


High Amplitude

# Pulse-Code Modulation

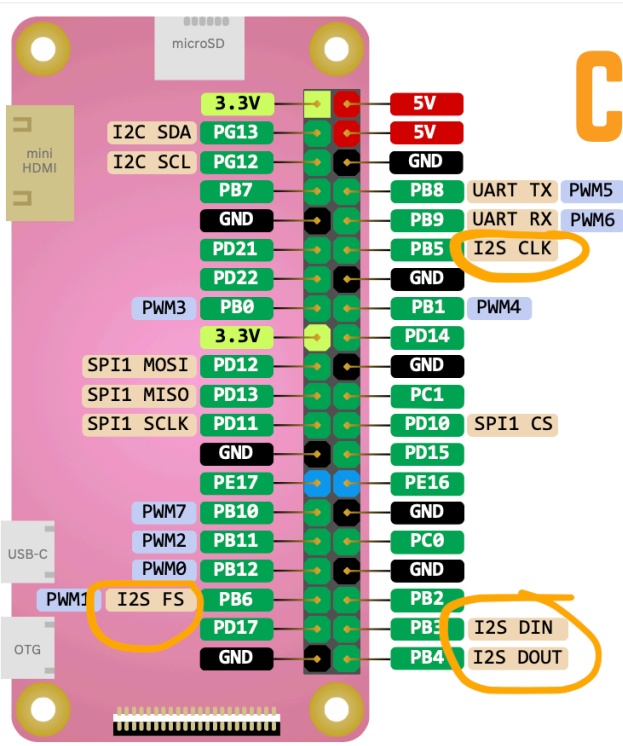
I2S/PCM standard for digital sound  
Quantization of sound wave into array  
of samples  
".wav" file is raw PCM data (MP3 is  
compressed form)

Playback needs sampling rate, bit depth,  
num channels  
CDs are PCM, sample rate 44.1  
kHz, 16-bit, stereo



Source: [Wikipedia](https://en.wikipedia.org/wiki/Pulse-code_modulation)

# I2S



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## 8 Audio

### 8.1 I2S/PCM

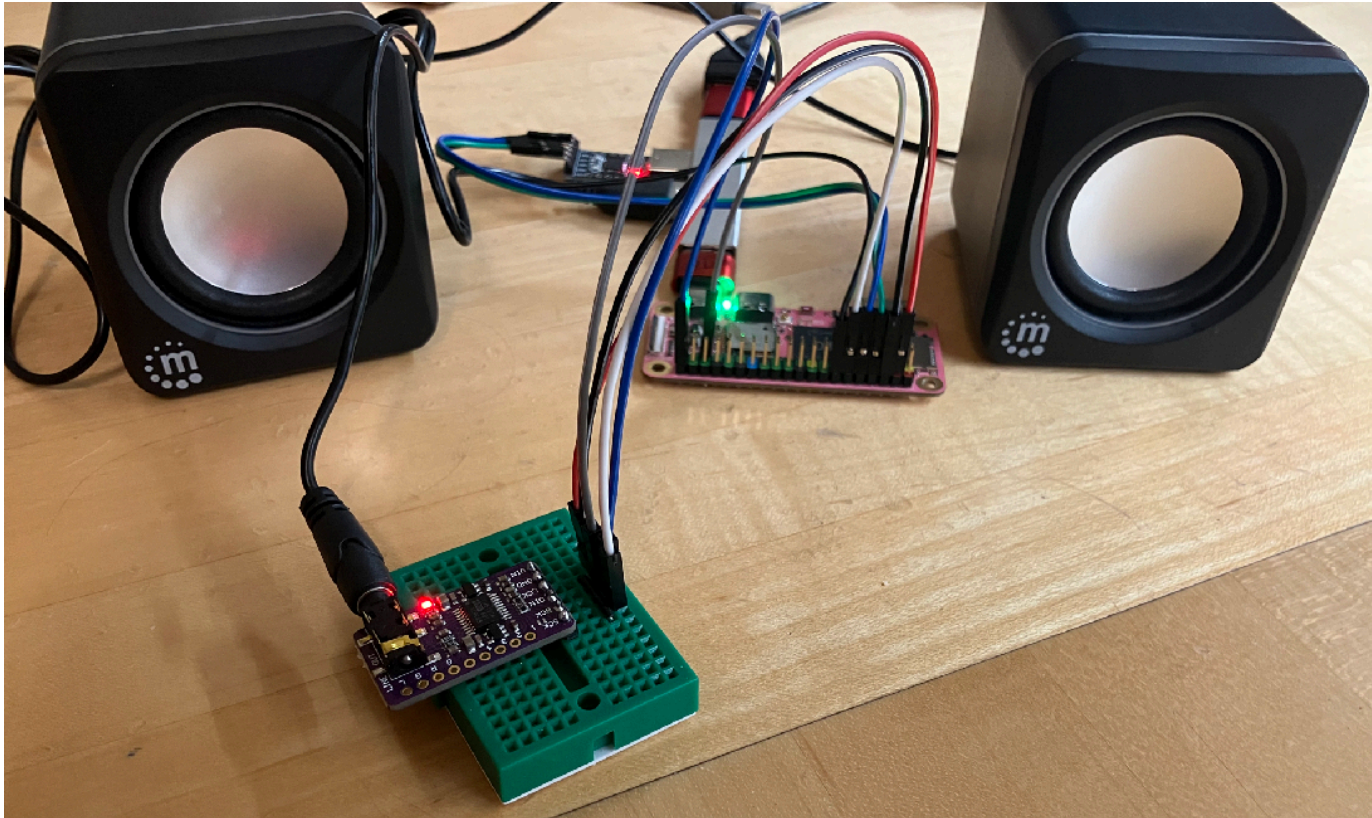
#### 8.1.1 Overview

The I2S/PCM controller is designed to transfer streaming audio-data between the system memory and the codec chip. The controller supports standard I2S format, Left-justified mode format, Right-justified mode format, PCM mode format, and TDM mode format.

The I2S/PCM controller includes the following features:

- Three I2S/PCM external interfaces (I2S0, I2S1, I2S2) for connecting external power amplifier and MIC ADC
- Compliant with standard Philips Inter-IC sound (I2S) bus specification
  - Left-justified, Right-justified, PCM mode, and Time Division Multiplexing (TDM) format
  - Programmable PCM frame width: 1 BCLK width (short frame) and 2 BCLKs width (long frame)

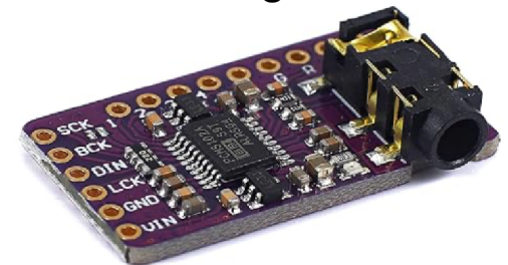
# Demo: I2S



Play wav file

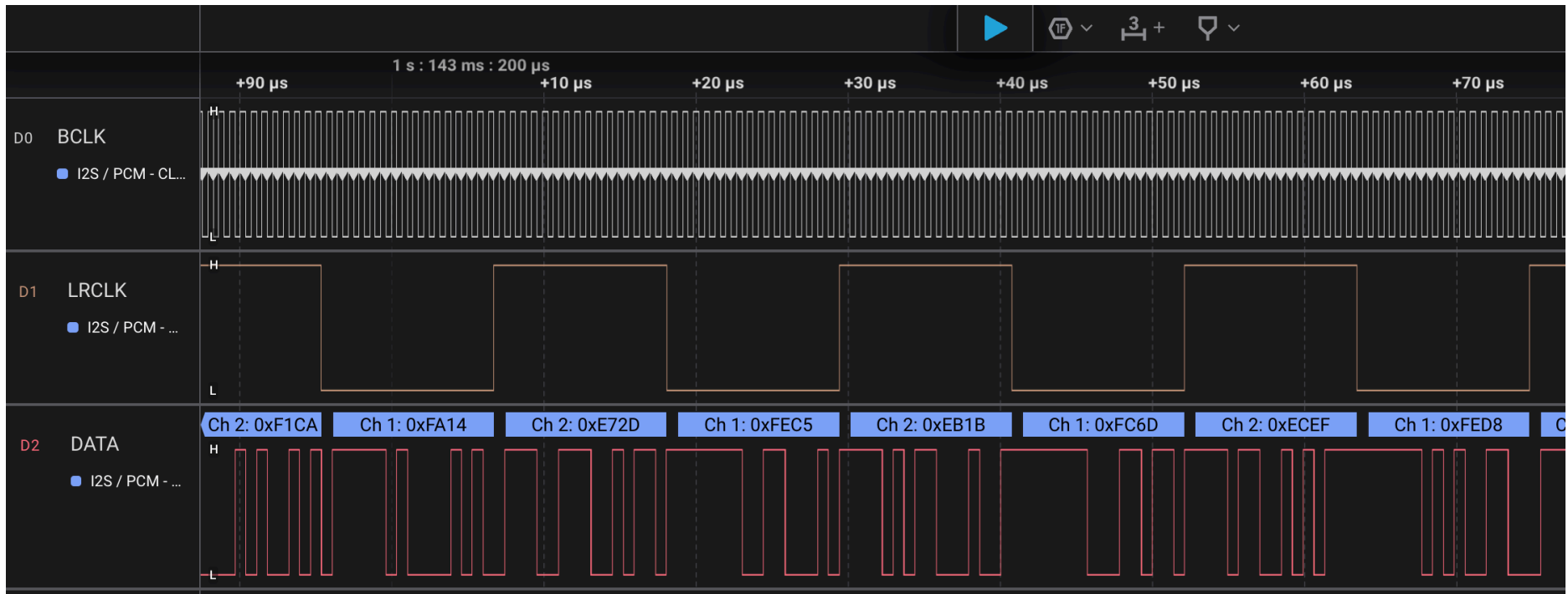
DAC: PCM5102A Stereo Digital Audio I2S

python script convert samples into C array compiled into program





# I2S protocol capture



Bit clock

LR clock (frame)

Data (sample value)

# For "real" music: MIDI

Musical Instrument Digital Interface

Simple protocol to control musical instruments

Emerged from electronic music and instruments in  
1970s

First version described in Keyboard magazine in 1982

# MIDI protocol

31.25 kbps 8-N-1 serial protocol

Commands are 1 byte, with variable parameters  
(c=channel, k=key, v=velocity, l=low bits, m=high bits)

Command	Code	Param	Param
Note on	1001cccc	0kkkkkkk	0vvvvvvv
Note off	1000cccc	0kkkkkkk	0vvvvvvv
Pitch bender	1110cccc	0l111111	0mmmmmmm